

# Wialon Combine

The Wialon Combine (v. 1.0.4) binary communication protocol was developed by Gurtam for use in personal and automotive GPS and GLONASS trackers which transmit data to a satellite monitoring server using the TCP or the UDP protocol.

## Specification

- Big-Endian is the order of bytes.
- Field\_name \* is an extensible one-byte field. A high-order bit indicates that there is an additional byte.
- Field\_name \*\* is an extensible two-byte field. A high-order bit indicates that there are two additional bytes.
- All data is received in binary format.
- Data transmission is implemented using the TCP and UDP protocols.

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## General Data Structure

<b>Size (Bytes)</b>	2	1-2	2	2-4			
<b>Section</b>	Head	Type*	Seq	Len**	Login (for UDP)	Data	CRC16

Head — 0x2424.

Type\*:

0 is Login,

1 is Data,

2 is Keep-Alive.

Seq. Sequence number (cyclic order 0 — 65535).

Len\*\*. The length of the *Data* field.

Data. Useful data. Depends on a packet type.

Login (for UDP). The field is provided only when using UDP.

CRC16. Checksum. It is calculated from the first byte of the head to the last byte of useful data.

## Required Server Response

The server responds to every received packet. The server response looks as follows:

<b>Size (Bytes)</b>	2	1	2
<b>Section</b>	Head	Code	Seq

Head — 0x4040.

Code. Response code.

Seq. The sequence number of the received packet.

Response code	Meaning
---------------	---------

0	Packet successfully registered
1	Authorization error
3	Packet not registered
4	CRC error
255	Device command

## Device Command Format

<b>Size (Bytes)</b>	2	1	2-4	4	1-2		2
<b>Section</b>	Head	Code	Len**	Time	Type*	Data	CRC16

Head — 0x4040.

Code — 0xFF.

Len. Packet length (*Time*, *Type* and *Data* fields).

Time. The time the message was sent.

Type. Command type.

Data. The additional parameters of the command.

CRC16. Checksum. It is calculated from the beginning of the head to the last byte of useful data.

<b>Command type</b>	<b>Meaning</b>
0	Custom command

The server does not require a response from the device to the command sent. If you want to send a response from the device, you can create a message of the *Custom parameters* type with the list of the required parameters. Subsequently, you can create the necessary notifications based on these parameters. You can also use the *Driver message* record type. In this case, the received message will be displayed in the chat with the driver.

## Login Packet

The *Login* packet looks as follows:

<b>Size (Bytes)</b>	1-2	1		
<b>Section</b>	Protocol version*	Flags	ID	Pwd

Protocol version\*: 1 is used currently.

Flags (bit field):

- 4 high-order bits are responsible for the type and size of the *ID* field.
- 4 low-order bits are responsible for the type and size of the *Pwd* field.

<b>Value</b>	<b>ID type</b>
1	unsigned short (2 bytes)
2	unsigned int (4 bytes)
3	unsigned long (8 bytes)
4	string (the last byte 0x00)

<b>Value</b>	<b>Pwd type</b>
0	password is missing
1	unsigned short (2 bytes)
2	unsigned int (4 bytes)
3	unsigned long (8 bytes)
4	string (the last byte 0x00)

## Keep-Alive Packet

The *Keep-Alive* packet contains only the first three packet fields

(*Head, Type, Seq*) and looks as follows:

<b>Size (Bytes)</b>	2	1-2	2
<b>Section</b>	Head	Type*	Seq

## Data Packet

The packet can contain several messages.

Each message includes time and length as well as a set of records.

In general, the message looks as follows:

<b>Size (Bytes)</b>	4	1	1-2		...	1-2	
<b>Section</b>	Time	Count	Sub- record type*	Sub- record	...	Type sub- record N	Sub- recordN

Time. The time the message was formed.

The time should be converted to UTC:0 without regard to the local time zone of the device. This is required in order to display the time correctly to the end user.

UTC is defined as the number of seconds that have elapsed since midnight (00:00:00 UTC), 1 January 1970.

Count. The number of records.

Sub-record type\*. The field which contains the record type code.

Sub-record. Data structure. A set of record fields depends on its type.

**Record types:**

Code	Record type
0	Custom Parameters
1	Position Data
2	I/O Data
3	Picture
4	LBS Parameters
5	Fuel Parameters
6	Temperature Parameters
7	CAN Parameters
8	Counter Parameters
9	Analog Parameters (ADC)
10	Driver Code Parameters
11	Tacho File
12	Driver message

## Custom Parameters Record Type

The record is a set of custom fields data which looks as follows:

<b>Size (Bytes)</b>	1-2	
<b>Section</b>	Count*	Params

Count\*. The number of custom fields in the record.

Params. A set of numbered parameters, each of which is registered as *param№*. It looks as follows:

<b>Bytes</b>	1-2	1	
<b>Section</b>	№*	Sensor type	Value

№. Sensor number.

Sensor type. The field which indicates the type of data in the *Value*

field. It has the following structure (for integer types only):

<b>Size (Bits)</b>	3	5
<b>Section</b>	10**X	Sensor type

For type 8 and more, the first three bits always equal 0.

10\*\*X. The degree of number 10. The value in the *Value* field will be divided by the number in this field.

Value. The sensor value according to the selected type.

### Sensor types:

Code	Sensor type
0	unsigned byte (1 byte)
1	unsigned short (2 bytes)
2	unsigned int (4 bytes)
3	unsigned int (8 bytes)
4	signed byte (1 byte)
5	signed short (2 bytes)
6	signed int (4 bytes)
7	signed long (8 bytes)
8	float (4 bytes)
9	double (8 bytes)
10	String (the last byte 0x00)

### Position Data Record Type

The record contains navigation data and looks as follows:

<b>Size (Bytes)</b>	4	4	2	2	2	1	2
<b>Section</b>	Lat	Lon	Speed	Course	Alt	Sats	HDOP

Lat. Latitude.

Lon. Longitude.

The coordinate value is of the *signed int* type. Example of value formation: a floating-point degree value multiplied by 1,000,000.

Speed. Speed value (km/h).

Course. Direction of movement (from 0 to 359 degrees).

Alt. Altitude. The *signed int* type.

Sats. The number of visible satellites.

HDOP. The Horizontal Dilution of Precision value multiplied by 100.

It shows the accuracy of the coordinates transmitted by the device. The smaller this value is, the more accurate the coordinates are.

## I/O Record Type

A bit field. Contains digital input and output values. Each bit of the number corresponds to one input or output. The I/O record looks as follows:

<b>Size (Bytes)</b>	4	4
<b>Section</b>	Inputs	Outputs

## Picture Record Type

The record contains a part of a picture made by the device camera.

The *Picture* record looks as follows:

<b>Size (Bytes)</b>	1	2-4	1-2		Len
<b>Section</b>	Ind*	Len**	Count*	Name	Bin

Ind\*. The index number of the transmitted picture block (numbering

from 0).

Len\*\*. The size of the picture block.

Count\*. The number of the last block (numbering from 0).

Name. The name of the transmitted picture. This is a text field which ends with 0x00.

Bin. Binary picture block.

## LBS Parameters Record Type

The *LBS Parameters* record looks as follows:

<b>Size (Bytes)</b>	1	
<b>Section</b>	Count	LBS params

Count. The number of the *LBS params* structures.

### LBS params:

<b>Size (Bytes)</b>	2	2	2	2	2	2
<b>Section</b>	MCC	MNC	LAC	Cell ID	Rx level	TA

MCC. Mobile Country Code.

MNC. Mobile Network Code.

LAC. Local Area Code. A local area is a group of base stations serviced by a base station controller.

Cell ID. A cell identifier assigned by the operator to every base station sector.

Rx level. The level of the input radio signal received by the GSM modem through this channel.

TA. Timing Advance. This parameter is used to compensate for the propagation delay as the signal travels between the GSM modem and the

base station. In effect, it is the distance to the base station.

## Fuel Parameter Record Type

The *Fuel Parameter* record looks as follows:

<b>Size (Bytes)</b>	1	
<b>Section</b>	Count	Fuel (the <i>Params</i> structure analog)

Count. The number of the *Fuel* structures.

Each parameter of this field will be registered with the name *fuel№*.

## Temperature Parameters Record Type

The *Temperature Parameters* record looks as follows:

<b>Size (Bytes)</b>	1	
<b>Section</b>	Count	Temp (the <i>Params</i> structure analog)

Count. The number of the *Temp* structures.

Each parameter of this field will be registered with the name *temp№*.

## CAN Parameters Record Type

The *CAN Parameters* record looks as follows:

<b>Size (Bytes)</b>	1	
<b>Section</b>	Count	CAN (the <i>Params</i> structure analog)

Count. The number of the *CAN* structures.

Each parameter of this field will be registered with the name *can№*.

## Counter Parameters Record Type

The *Counter Parameters* record looks as follows:

<b>Size (Bytes)</b>	1	
<b>Section</b>	Count	Counter (the <i>Params</i> structure analog)

Count. The number of the *Counter* structures.

Each parameter of this field will be registered with the name *counter№*.

## Analog Parameters (ADC) Record Type

The *Analog Parameters (ADC)* record looks as follows:

<b>Size (Bytes)</b>	1	
<b>Section</b>	Count	ADC (the <i>Params</i> structure analog)

Count. The number of the *ADC* structures.

Each parameter of this field will be registered with the name *adc№*.

## Driver Code Parameters Record Type

The *Driver Code Parameters* record looks as follows:

<b>Size (Bytes)</b>	1	
<b>Section</b>	Count	Driver code (the <i>Params</i> structure analog)

Count. The number of the *Driver code* structures.

Each parameter of this field will be registered with the name *driver\_code№* \*.

## Tacho File Record Type

The record contains a part of a tachograph file. It looks as follows:

<b>Size (Bytes)</b>	1	2-4	1	Len
<b>Section</b>	Ind*	Len**	Count*	Bin

Ind\*. The index number of the transmitted block (numbering from 0).

Len\*\*. The size of the transmitted block.

Count\*. The number of the last block (numbering from 0).

Bin. The binary block of the tachograph file.

## Driver Message Record Type

The record contains a message to the driver. It looks as follows:

<b>Size (Bytes)</b>	Endian 0x00
<b>Section</b>	Text

Text. The message to the driver. The string ends with 0x00.

## CRC 16 (C Code Example):

```
static const unsigned short crc16_table[256] =
{
    0x0000,0xC0C1,0xC181,0x0140,0xC301,0x03C0,0x0280,0xC241,
    0xC601,0x06C0,0x0780,0xC741,0x0500,0xC5C1,0xC481,0x0440,
    0xCC01,0x0CC0,0x0D80,0xCD41,0x0F00,0xCF41,0xCE81,0x0E40,
    0x0A00,0xCAC1,0xCB81,0x0B40,0xC901,0x09C0,0x0880,0xC841,
    0xD801,0x18C0,0x1980,0xD941,0x1B00,0xDB41,0xDA81,0x1A40,
    0x1E00,0xDEC1,0xDF81,0x1F40,0xDD01,0x1DC0,0x1C80,0xDC41,
    0x1400,0xD4C1,0xD581,0x1540,0xD701,0x17C0,0x1680,0xD641,
    0xD201,0x12C0,0x1380,0xD341,0x1100,0xD1C1,0xD081,0x1040,
    0xF001,0x30C0,0x3180,0xF141,0x3300,0xF3C1,0xF281,0x3240,
    0x3600,0xF6C1,0xF781,0x3740,0xF501,0x35C0,0x3480,0xF441,
    0x3C00,0xFCC1,0xFD81,0x3D40,0xFF01,0x3FC0,0x3E80,0xFE41,
    0xFA01,0x3AC0,0x3B80,0xFB41,0x3900,0xF9C1,0xF881,0x3840,
    0x2800,0xE8C1,0xE981,0x2940,0xEB01,0x2BC0,0x2A80,0xEA41,
    0xEE01,0x2EC0,0x2F80,0xEF41,0x2D00,0xEDC1,0xEC81,0x2C40,
    0xE401,0x24C0,0x2580,0xE541,0x2700,0xE7C1,0xE681,0x2640,
    0x2200,0xE2C1,0xE381,0x2340,0xE101,0x21C0,0x2080,0xE041,
    0xA001,0x60C0,0x6180,0xA141,0x6300,0xA3C1,0xA281,0x6240,
    0x6600,0xA6C1,0xA781,0x6740,0xA501,0x65C0,0x6480,0xA441,
    0x6C00,0xACC1,0xAD81,0x6D40,0xAF01,0x6FC0,0x6E80,0xAE41,
    0xAA01,0x6AC0,0x6B80,0xAB41,0x6900,0xA9C1,0xA881,0x6840,
    0x7800,0xB8C1,0xB981,0x7940,0xBB01,0x7BC0,0x7A80,0xBA41,
    0xBE01,0x7EC0,0x7F80,0xBF41,0x7D00,0xBDC1,0xBC81,0x7C40,
    0xB401,0x74C0,0x7580,0xB541,0x7700,0xB7C1,0xB681,0x7640,
    0x7200,0xB2C1,0xB381,0x7340,0xB101,0x71C0,0x7080,0xB041,
    0x5000,0x90C1,0x9181,0x5140,0x9301,0x53C0,0x5280,0x9241,
    0x9601,0x56C0,0x5780,0x9741,0x5500,0x95C1,0x9481,0x5440,
    0x9C01,0x5CC0,0x5D80,0x9D41,0x5F00,0x9FC1,0x9E81,0x5E40,
    0x5A00,0x9AC1,0x9B81,0x5B40,0x9901,0x99C0,0x5880,0x9841,
    0x8801,0x48C0,0x4980,0x8941,0x4B00,0x8BC1,0x8A81,0x4A40,
    0x4E00,0x8EC1,0x8F81,0x4F40,0x8D01,0x4DC0,0x4C80,0x8C41,
    0x4400,0x84C1,0x8581,0x4540,0x8701,0x47C0,0x4680,0x8641,
    0x8201,0x42C0,0x4380,0x8341,0x4100,0x81C1,0x8081,0x4040
};

unsigned short crc16 (const void *data, unsigned data_size)
{
    if (!data || !data_size)
        return 0;

    unsigned short crc = 0;
    unsigned char* buf = (unsigned char*)data;

    while (data_size--)
        crc = (crc >> 8) ^ crc16_table[(unsigned char)crc ^ *buf++];

    return crc;
}
```

## Message Examples

### Login Message Example

The original message:

```
242400004000130144737472696E675F646576696365696400009B93
```

2424 is the head of the packet;

00 is the message type (Login);

0040 is the sequence number of the message;

0013 is the length of the message (the field is extensible, but because there is no high-order bit, the length is two bytes; otherwise, it would be 4 bytes);

01 is the protocol version;

44 is the flag. Binary representation (0100 0100), the *ID* type is 4 String, the *Pwd* type is 4 String;

737472696E675F646576696365696400 is the device ID. According to the protocol, the last byte after the string field is 0x00 to distinguish the border of the text data;

00 is the end byte of the password because in accordance with the flag, the password is transmitted. Regardless of whether there is a password value or not, there should be an end byte because in accordance with the flag, the packet has a password;

9B93 is the CRC.

### Server Response Message Example

The original message: 

```
40400000040
```

4040 is the head of the packet;

00 is a response code (packet successfully registered);

0040 is the sequence number of the message.

## Keep-Alive Message Example

The original message: 2424020011

2424 is the head of the packet;

02 is the message type (Keep-Alive);

0011 is the sequence number of the message.

## Data Message Example

The original message:

```
24240149F300665CF6150303010350A6EC023C5938000F012C01060B006402000000  
010000000000050100000200070300040861367E09610FEF5CF6150103010350A6C8  
023C59880000011F01060C005E0200000001000000000005010000020007030005086  
1367409610FEC0140
```

2424 is the head of the packet;

01 is the message type (Data);

49F3 is the sequence number of the message;

0066 is the length of useful data;

5CF61503 is time;

03 is the number of records;

01 is the *Position Data* record type;

350A6EC is a latitude of 55.61726 degrees. The value has been transferred to the decimal system (55617260) and divided by 1,000,000;

23C5938 is a longitude of 37.509432 degrees. The value has been transferred to the decimal system (37509432) and divided by 1,000,000;

000F is a speed of 15 km / h;

012C is a course of 300 degrees;

0106 is an altitude of 262 meters;  
 0B is the number of satellites (11);  
 0064 is 1 HDOP. The value has been transferred to the decimal system (100) and divided by 100;  
 02 is the *I/O Data* record type;  
 00000001 refers to inputs;  
 00000000 refers to outputs;  
 00 is the *Custom Parameters* record type;  
 05 is the number of records;  
 01 is the number of the sensor;  
 00 is the sensor type (0 is an unsigned byte (1 byte));  
 00 is the value of the sensor;  
 The final parameter form in Wialon: param1=0.  
 02 00 07 is param2=7;  
 03 00 04 is param3=4;  
 08 is the number of the sensor;  
 61 is the sensor type. Here the sensor type has an additional multiplier, that is three high-order 'X' bits. In a binary representation 0x61 => 0110 0001. According to the protocol, 10\*\*X is a degree of number 10. The parameter value will be divided by 10\*\*X;  
 367E is param8=13.95;  
 09 61 0FEF is param9=4.079;  
 5CF61501 is time;  
 03 is the number of records;  
 01 is the *Position Data* record type;  
 0350A6C8 is a latitude of 55.617224 degrees. The value has been transferred to the decimal system (55617224) and divided by 1,000,000;  
 023C5988 is a longitude of 37.509512 degrees. The value has been transferred to the decimal system (37509512) and divided by 1,000,000;  
 0000 is speed;





```
109dab599ba881bcd1d6d7de401e1cfe3fac60cdf97595269a6f6620691c7f7c54b7297a3
1aba4778e9baa386bbaabf28c95716bbf6c022a60346c433c5988d55c424898068fb7bc7
6a9888a938cae6ddb8b042f38282b38c5aefdb029bf6fd1ff00ffd9684f
```

Message №1 is used as an example of data parsing for a file transfer. For the other messages (№2 and №3), the principle remains the same. Data parsing:

2424 is the head of the packet;

01 is the message type (*Data*);

0001 is the sequence number (cyclic order 0 — 65535);

0215 is the length of the *Data* field;

5CF78ACF is the time the message was formed;

01 is the number of records;

03 is the *Picture* record type;

00 is the index number of the transmitted block (numbering from 0);

0200 is the size of the picture block (only the binary part of the picture block);

02 is the number of the last block (numbering from 0);

746573745F696D61676500 is the name of the transmitted picture. A text field, ends with 0x00;

ffd8ffe000104a4649 ... f13e is the binary part of the picture;

fcea is the CRC.

## UDP Message Example

The message example is based on the *Data* type.

```
2424 01 49F3 0066 0144737472696E675F64657669636569640000
5CF6150303010350A6EC023C5938000F012C01060B00640200000001000000000005
0100000200070300040861367E09610FEF5CF6150103010350A6C8023C5988000001
1F01060C005E02000000010000000000050100000200070300050861367409610FEC
3EA9
```

2424 is the head of the packet;

01 is the message type (Data);

49F3 is the sequence number of the message;

0066 is the length of the *Data* field;

01 44 737472696E675F646576696365696400 00 is the *login* structure.

(Contains:

01 is the protocol version,

44 is the flag,

737472696E675F646576696365696400 is the ID,

00 is the password).

This is followed by the data structure without any changes. When calculating the CRC, the login is also included.